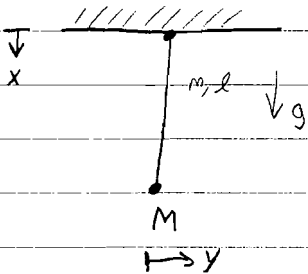
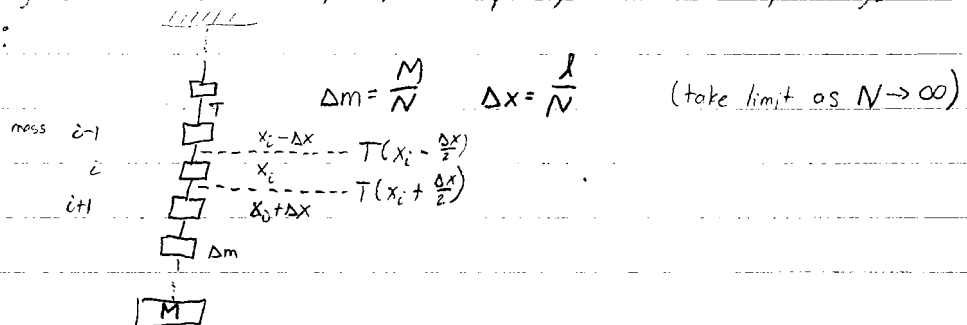


May 2007 #3 (CM)

mass M hanging from a string of mass m , length l , gravity g
 upper end of string fixed, $M \gg m$

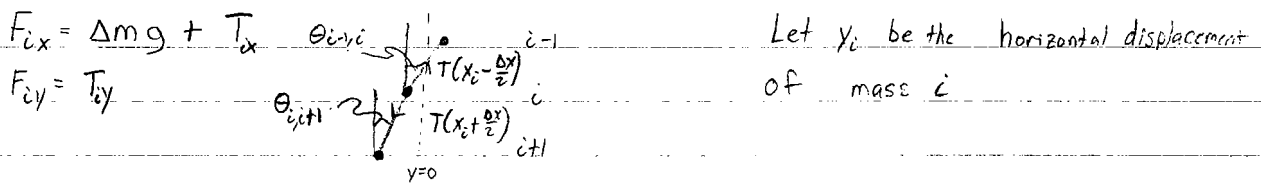


a. Model the string as N elements Δm , separated by Δx , connected by strings with tension $T(x)$:



Assume small transverse oscillations:

Force balance on mass i : $\Delta m \vec{a}_i = \vec{F}_i$



$$T_{ix} = -T(x_i - \frac{\Delta x}{2}) \cos \theta_{i-1,i} + T(x_i + \frac{\Delta x}{2}) \cos \theta_{i,i+1}$$

$$T_{iy} = T(x_i - \frac{\Delta x}{2}) \sin \theta_{i-1,i} - T(x_i + \frac{\Delta x}{2}) \sin \theta_{i,i+1}$$

$$\sin \theta_{i-1,i} = \frac{y_{i-1} - y_i}{\sqrt{\Delta x^2 + (y_{i-1} - y_i)^2}} \quad \cos \theta_{i-1,i} = \frac{\Delta x}{\sqrt{\Delta x^2 + (y_{i-1} - y_i)^2}}$$

Under the small transverse oscillation assumption, the angles are small, and to first order, $\sin \theta_{i-1,i} = \frac{y_{i-1} - y_i}{\Delta x}$, $\cos \theta_{i-1,i} = 1$

Taylor Expanding $T(x_i - \frac{\Delta x}{2})$ about x_i ,

$$T_{ix} = T(x_i) + \frac{\partial T}{\partial x} \frac{\Delta x}{2} - T(x_i) + \frac{\partial T}{\partial x} \frac{\Delta x}{2} = \frac{\partial T}{\partial x} \Delta x$$

$$T_{iy} = \left(T - \frac{\partial T}{\partial x} \frac{\Delta x}{2} \right) \frac{y_{i-1} - y_i}{\Delta x} - \left(T + \frac{\partial T}{\partial x} \frac{\Delta x}{2} \right) \frac{y_i - y_{i+1}}{\Delta x} = T \frac{y_{i+1} - 2y_i + y_{i-1}}{\Delta x} + \frac{\partial T}{\partial x} \frac{y_{i+1} - y_{i-1}}{2}$$

$$T_{cx} = \frac{dT}{dx} \Delta x$$

$$T_{cy} = \Delta x T \frac{y_{c+1} - 2y_c + y_{c-1}}{(\Delta x)^2} + \Delta x \frac{dT}{dx} \frac{y_{c+1} - y_{c-1}}{2\Delta x}$$

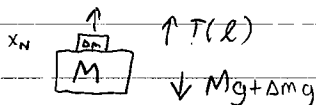
$$\Delta m \ddot{x}_c = \Delta m g + \Delta x \frac{dT}{dx}$$

In small oscillations, the vertical displacement is negligible, so $\ddot{x}_c = 0$

$$0 = \frac{m}{N} g + \frac{l}{N} \frac{dT}{dx} \quad [\text{Passage to Continuum limit; becomes exact}]$$

$$\frac{dT}{dx} = -\frac{mg}{l} = -\mu g \quad \text{where } \mu = \frac{m}{l} \text{ is mass per unit length}$$

Boundary conditions: look at the last mass $\Delta m/M$ at the bottom



$$T(l) = Mg + \Delta mg \approx Mg$$

$$T = -\frac{mgx}{l} + C \quad T(l) = Mg = -mg + C \quad C = Mg + mg$$

$$T(x) = Mg + mg\left(1 - \frac{x}{l}\right) = g\left[M + m\left(1 - \frac{x}{l}\right)\right]$$

$$T(x) \approx Mg \quad \text{for } M \gg m \text{ (constant)}$$

$$\Delta m \ddot{y}_c = \Delta x T \frac{y_{c+1} - 2y_c + y_{c-1}}{(\Delta x)^2} + \Delta x \frac{dT}{dx} \frac{y_{c+1} - y_{c-1}}{2\Delta x} \quad N \rightarrow \infty, \text{ continuum}$$

$$y_c(t) \rightarrow y(x,t)$$

$$\frac{m}{N} \ddot{y} = \frac{l}{N} T \frac{\partial^2 y}{\partial x^2} + \frac{l}{N} \frac{dT}{dx} \frac{\partial y}{\partial x}$$

T is approx. constant, so $\frac{dT}{dx} \sim$ negligible [that term can be shown to be smaller by $\frac{m}{M}$]

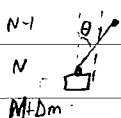
$$\frac{m}{lT} \frac{\partial^2 y}{\partial t^2} = \frac{\partial^2 y}{\partial x^2}$$

$$\frac{l}{v^2} \frac{\partial^2 y}{\partial t^2} = \frac{\partial^2 y}{\partial x^2}$$

$$v^2 = \frac{lT}{m} = \frac{T}{\mu} = \frac{lgM}{m}$$

Boundary conditions: $y(0,t)$ (fixed)

$y(l,t) = 0$



$$(M + \Delta m) \ddot{y}_N = T_{N+1} - T_N \rightarrow \frac{M \partial^2 y}{\partial t^2} = -T \frac{\partial y}{\partial x}(l,t)$$

$$\Rightarrow \frac{\partial^2 y(l,t)}{\partial t^2} = -g \frac{\partial y(l,t)}{\partial x}$$

b. $\frac{1}{v^2} \frac{\partial^2 y}{\partial t^2} = \frac{\partial^2 y}{\partial x^2}$ normal modes are oscillations' sines/cosines

$y(0)=0$, so use $\sin kx$

$$y(x,t) = \sin(kx) \cos(\omega t + \phi) \quad \omega^2 = k^2 v^2$$

$$\frac{\partial^2 y}{\partial t^2}(l,t) = -g \frac{\partial y}{\partial x}(l,t)$$

$$-\omega^2 \sin(kl) = g k \cos kl$$

$$-k^2 v^2 \sin(kl) = g k \cos kl$$

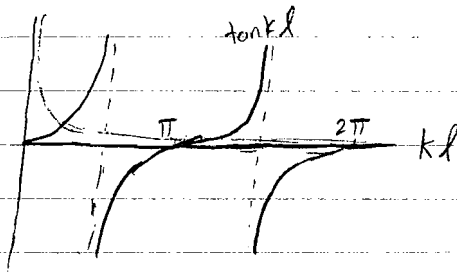
$$\Rightarrow \tan kl = \frac{g}{k v^2} = \frac{g l}{k l v^2}$$

$$\frac{g l}{v^2} = \frac{g l}{l g M/m} = \frac{m}{M}$$

$$\boxed{\tan kl = \frac{m/M}{kl}}$$

Equation giving the solutions for k

c. $\frac{m}{M}$ small:



Solve $\tan x = \frac{\alpha}{x}$ where $\alpha \ll 1$

The solutions are near $n\pi$, as can be seen graphically. For large n , the approximation $n\pi$ gets more accurate.

Linearize $\tan x$ about $n\pi$: $\tan(n\pi) = 0$ $\frac{d \tan(x)}{dx} \Big|_{n\pi} = \sec^2(n\pi) = 1$

$$\tan x \approx (x - n\pi)$$

$$x - n\pi = -\frac{\alpha}{x} \quad x \approx n\pi, \text{ so replace } x \text{ with } n\pi$$

$$x = n\pi + \frac{\alpha}{n\pi}$$

First solution: $x^2 = \alpha = k^2 l^2$

$$\omega = kv = \frac{\sqrt{\alpha}}{l} \cdot v = \frac{\sqrt{m/M}}{l} \cdot \sqrt{\frac{lgM}{m}} = \sqrt{\frac{g}{l}}$$

Second solution: $x \approx \pi + \frac{\alpha}{\pi} \quad kl \approx \pi \left(1 + \frac{\alpha}{\pi^2}\right) \quad \frac{2\pi}{\lambda} = \frac{\pi}{l} \left(1 + \frac{\alpha}{\pi^2}\right)$

$$\lambda = \frac{2l}{\left(1 + \frac{\alpha}{\pi^2}\right)} \quad \text{Wavelength nearly } 2l.$$

