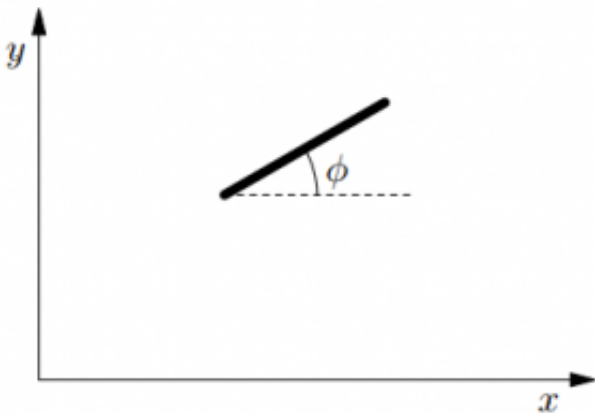


J98M.3

Problem:

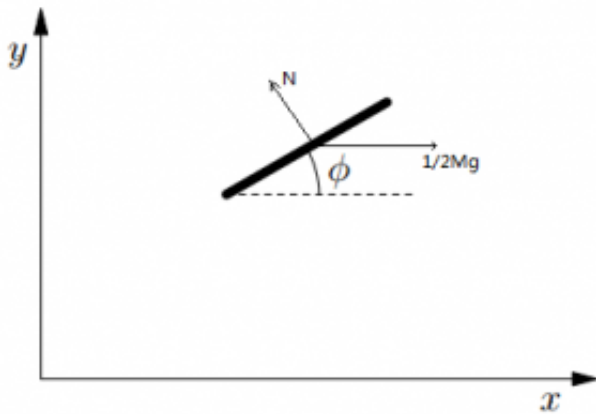
As a simplified model for the motion of a skate, assume that the blade experiences no friction when it moves along itself and/or turns around its center. The blade cannot move translational normal to itself. Now consider a skate moving on an icy inclined plane which makes a 30° degree angle with the horizontal. In view of the assumption above, you may think of the blade as a thin uniform rod of mass M moving on the plane under the influence of gravity subject to the constraint that it cannot move translational normal to itself. Introduce Cartesian coordinates x and y on the plane, with x pointing down the incline. The blade is characterized by its center of mass position (x, y) , and the angle ϕ it makes with the x -axis.



1. Write down the equations of motion including the reaction force normal to the blade.
2. Write down the constraint on the motion in terms of x , y , ϕ , and their time derivatives.
3. At time $t = 0$; $x = y = \phi = \dot{x} = \dot{y} = 0$ and $\dot{\phi} = \omega$. Find the subsequent trajectory. Hint: The reaction force normal to the blade is proportional to $\sin \omega t$.

Solution:**Equations of Motion**

The forces exerting on the blade are as shown in Figure 2. Note that there are no net torque on the blade, the ϕ coordinate just undergoes free motion. Given that the initial rotation around the center has angular velocity ω , we can easily write down:



$$\phi = \omega t \quad (1)$$

$$\ddot{\phi} = 0 \quad (2)$$

Note that since we are on an incline of 30 degrees, the gravitational force is only $\frac{1}{2} Mg$. Next, simply apply Newton's second law, we write down the EOMs with normal force N :

$$M\ddot{x} = \frac{1}{2} Mg - N \sin \omega t \quad (3)$$

$$M\ddot{y} = N \cos \omega t \quad (4)$$

Constraint of motion

The only constraint on the motion is that the blade cannot move translational normal to itself. Such a constraint can be written as the relation between the x direction and y direction velocity:

$$\frac{\dot{y}}{\dot{x}} = \tan \phi = \tan \omega t \quad (5)$$

With the EOMs written, it remains to solve them. Take $N = A \sin \omega t$ (suggested by Hint), where A is the normal force amplitude to be determined, we have:

$$\ddot{x} = \frac{1}{2}g - \frac{A}{M} \sin^2 \omega t \quad (6)$$

$$\ddot{y} = \frac{A}{M} \sin \omega t \cos \omega t \quad (7)$$

Integrate (6) and (7) once, we have:

$$\dot{x} = \frac{1}{2}gt - \frac{At}{2M} + \frac{A \sin 2\omega t}{4\omega M} \quad (8)$$

$$\dot{y} = \frac{A(1 - \cos 2\omega t)}{4\omega M} \quad (9)$$

Using (5), we solve for A :

$$\frac{1}{2}gt - \frac{At}{2M} + \frac{A \sin 2\omega t}{4\omega M} = \frac{A(1 - \cos 2\omega t)}{4\omega M \tan \omega t} \quad (10)$$

It's easy to see that $A = Mg$. Thus the normal force $N = Mg \sin \omega t$.

Now integrate (8) and (9) to obtain the trajectory.

$$x = \frac{g}{8\omega^2} (1 - \cos 2\omega t) \quad (11)$$

$$y = \frac{g}{4\omega^2} (2\omega t - \sin 2\omega t) \quad (12)$$

One thought on "J98M.3"



Good, correct solution.

But you missed an extra factor of $\frac{1}{2}$ in (12). Check it one more time.
