

## Prelims Solutions

### Problem J14M2

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## 1

In the figure  $\Omega$  is in the  $zy$  plane so we have symmetry of the ring in the  $x$  direction (unclear what  $\alpha$  is for...). Consider an azimuthal angle  $\phi$  on the ring measured using  $\Omega$  as the "z axis" and  $\phi = 0$  corresponding to the point on the ring farthest from the Sun. A small angle on the ring has mass  $\frac{\delta M d\phi}{2\pi}$ , has coordinates  $(x, y, z) = R_r(\sin(\phi), -\cos(\phi)\cos(\theta), \cos(\phi)\sin(\theta))$ . The torque is thus:

$$\vec{\tau} = \int_0^{2\pi} \vec{r} \times \vec{F}_g = \int_0^{2\pi} \frac{G \frac{\delta M d\phi}{2\pi} M_s}{((R_r \sin(\phi))^2 + (R_{es} + R_r \cos(\phi)\cos(\theta))^2 + (R_r \cos(\phi)\sin(\theta))^2)^{\frac{3}{2}}} \\ * (R_r \sin(\phi), -R_r \cos(\phi)\cos(\theta), R_r \cos(\phi)\sin(\theta)) \times (-R_r \sin(\phi), R_{es} + R_r \cos(\phi)\cos(\theta), -R_r \cos(\phi)\sin(\theta))$$

By symmetry,  $\tau_y = 0$  and  $\tau_z = 0$ . The  $x$  component of the cross product gives  $(-R_r \cos(\phi)\sin(\theta))(-R_r \cos(\phi)\cos(\theta)) - (R_{es} + R_r \cos(\phi)\cos(\theta))(R_r \cos(\phi)\sin(\theta)) \approx -R_{es}R_r \cos(\phi)\sin(\theta)$  to first order in  $R_r$ . Approximating the distance from the Sun using only the  $y$  coordinate gives:

$$\tau = - \int_0^{2\pi} \frac{G \frac{\delta M}{2\pi} M_s R_{es} R_r \cos(\phi)\sin(\theta)}{(R_{es} + R_r \cos(\phi)\cos(\theta))^3} d\phi = - \int_0^{2\pi} \frac{G \frac{\delta M}{2\pi} M_s R_{es} R_r \cos(\phi)\sin(\theta)}{R_{es}^3 (1 + \frac{R_r}{R_{es}} \cos(\phi)\cos(\theta))^3} d\phi \\ \approx - \frac{G \frac{\delta M}{2\pi} M_s R_r \sin(\theta)}{R_{es}^2} \int_0^{2\pi} \cos(\phi) (1 - 3 \frac{R_r}{R_{es}} \cos(\phi)\cos(\theta)) d\phi = - \frac{G \frac{\delta M}{2\pi} M_s R_r \sin(\theta)}{R_{es}^2} (0 - 3 \frac{R_r}{R_{es}} \cos(\theta)(\pi))$$

Hence,

$$\tau_x = \frac{3G\delta M M_s R_r^2 \sin(\theta)\cos(\theta)}{2R_{es}^3}$$

## 2

To first order in  $\frac{\delta M}{M}$ ,  $L = \frac{2}{5}MR_o^2\Omega$ .

$$\tau_x = \left(\frac{d\vec{L}}{dt}\right)_x = \frac{L \sin(\theta) d\theta}{dt} = L \sin(\theta) \omega_p \rightarrow$$

$$\omega_p = \frac{\tau_x}{L \sin(\theta)} = \frac{15G\delta M M_s R_r^2 \cos(\theta)}{4M\Omega R_o^2 R_{es}^3}$$

i.e. counterclockwise around  $z$ . This is the instantaneous precession I think because the torque is probably going to change as the ring/earth moves in its orbit...