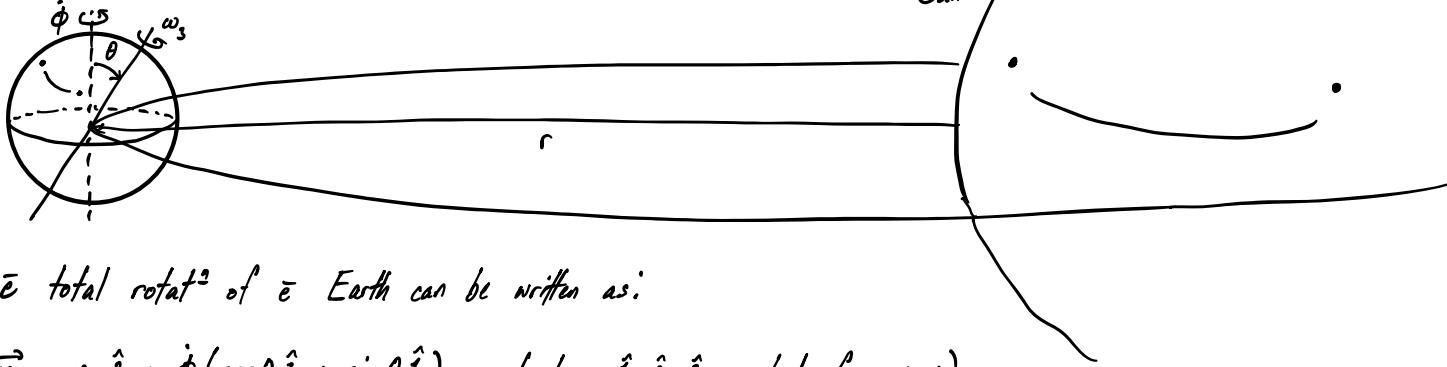


J13M.3 (Precess² of Equinoxes)

(a)



The total rotation of the Earth can be written as:

$$\vec{\omega} = \omega_3 \hat{z} + \dot{\phi} (\cos \theta \hat{z} + \sin \theta \hat{i}) \quad (\text{where } \hat{i}, \hat{j}, \hat{k} \text{ are body frame axes})$$

$$= (\omega_3 + \dot{\phi} \cos \theta) \hat{z} + \dot{\phi} \sin \theta \hat{i}$$

\Rightarrow the rotational KE of the Earth is:

$$T_{\text{rot}} = \frac{1}{2} I_3 (\omega_3 + \dot{\phi} \cos \theta)^2 + \frac{1}{2} I_i \dot{\phi}^2 \sin^2 \theta$$

Denote the mass of the Earth by m , & the orbital angular frequency by ω_0 .

$$L = \frac{1}{2} m r^2 + \frac{1}{2} m r^2 \omega_0^2 + \frac{GMm}{r} - \frac{GM(I_3 - I_i)}{2r^3} \left(\frac{1}{2} - \frac{3}{2} \cos^2 \theta \right) \quad \begin{matrix} \text{this is } P_2(\cos \theta) \\ \text{so it suggests the} \\ \text{torque is due to a quadrupole} \\ \text{moment (i.e. oblateness of the Earth).} \end{matrix}$$

$$+ \frac{1}{2} I_3 (\omega_3 + \dot{\phi} \cos \theta)^2 + \frac{1}{2} I_i \dot{\phi}^2 \sin^2 \theta$$

(b) To obtain $\dot{\phi}$, we should evaluate the Euler-Lagrange equations.

Firstly, \because there is no otherwise stated information in the question, I'm going to assume a circular orbit.

$$\Rightarrow \dot{r} = 0, \omega_0 = \text{const}, r = \text{const.}$$

Now, for the Euler-Lagrange equations:

$$\phi \text{ eq}^2: \frac{d}{dt} \left[I_3 (\omega_3 + \dot{\phi} \cos \theta) (\cos \theta) + I_i \dot{\phi} \sin^2 \theta \right] = 0$$

$$\Rightarrow I_3 \cos \theta \dot{\omega}_3 + I_3 \cos^2 \theta \ddot{\phi} + I_i \ddot{\phi} \sin^2 \theta = 0$$

But this is hard to work w/ so fuck it.

$\theta \text{ eq}^2$: Note that L is independent of $\dot{\theta}$ because we assumed no nutation.

$$\Rightarrow \frac{\partial L}{\partial \theta} = 0 = \frac{3}{2} \frac{GM(I_3 - I_i)}{r^3} (-\cos \theta \sin \theta) + I_3 (\omega_3 + \dot{\phi} \cos \theta) (-\dot{\phi} \sin \theta) + I_i \dot{\phi}^2 \sin \theta \cos \theta$$

$$\Rightarrow 0 = \frac{3GM(I_3 - I_i)}{2r^3} + \frac{I_3 \omega_3 \dot{\phi}}{\cos \theta} + I_3 \dot{\phi}^2 - I_i \dot{\phi}^2$$

Then, invoke the fact that $\dot{\phi} \ll \omega_3$ to drop the last two terms.

$$\Rightarrow \dot{\phi} \approx - \frac{3GM(I_3 - I_i) \cos \theta}{2I_3 \omega_3 r^3}$$

We also assumed this was a circular orbit, so: $\omega_0^2 = \frac{GMm}{r^3}$

$$\Rightarrow \dot{\phi} \approx -\frac{3\omega_0^2(I_3 - I_1) \cos \theta}{2I_3 \omega_3}$$

$$\Rightarrow \frac{\dot{\phi}}{\omega_0} \approx -\frac{3\omega_0}{2I_3 \omega_3} (I_3 - I_1) \cos \theta$$

(c) Look² from above, we can see $\dot{\phi} \sim -\alpha$, where α is a positive const.

$\Rightarrow \dot{\phi}$ points downward, so \vec{e} precess² is clockwise (given we are look² from where \vec{e} orbit looks CCW).

This is opposite \vec{e} orbital direct².

(d) As an estimate, $\left| \frac{\dot{\phi}}{\omega_0} \right| \sim \frac{3}{2} \cdot 3 \times 10^{-3} \cdot \frac{T_3}{T_0} \cos(23.5^\circ)$, where $\frac{T_3}{T_0}$ is just $\frac{1}{365}$

$$\sim 4.5 \times 10^{-3} \cdot \frac{1}{365} \cos(23.5^\circ) \sim 10^{-3} \cdot 10^{-2} \cdot 1$$
$$\sim 10^{-5}$$

$$\Rightarrow \frac{1 \text{ year}}{T_{\text{prec.}}} \sim 10^{-5} \Rightarrow T_{\text{prec.}} \sim 10^5 \text{ yr} > 26000 \text{ yrs}.$$