

## Prelims Solutions

### Problem J10M1

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#### 1

The coordinates of the COM are  $x = s\cos\alpha + \frac{l}{2}\sin\theta$ ,  $y = -(s\sin\alpha + \frac{l}{2}\cos\theta)$  (my  $\theta$  is negative of theirs). The Lagrangian of the system is  $L = T - U = KE_{COM} + KE_{Rotation} - mgy \rightarrow$

$$L = \frac{1}{2}m(\dot{s}^2 + (\frac{l}{2})^2\dot{\theta}^2 + s\dot{\theta}\cos\theta\cos\alpha - s\dot{\theta}\sin\theta\sin\alpha) + \frac{1}{2}I\dot{\theta}^2 + mg(s\sin\alpha + \frac{l}{2}\cos\theta)$$

#### 2

Fixed  $\theta$  means  $\dot{\theta} = 0$  and  $\ddot{\theta} = 0$  in the EL equations. The EL equation for  $s$  is :

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{s}} = \frac{d}{dt} (m\dot{s} + l\dot{\theta}\cos\theta\cos\alpha - l\dot{\theta}\sin\theta\sin\alpha) = m\ddot{s} + \ddot{\theta}(\dots) + \dot{\theta}(\dots) = \frac{\partial L}{\partial s} = mg\sin\alpha \rightarrow \ddot{s} = g\sin\alpha$$

The EL equation for  $\theta$  is :

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}} = (m(\frac{l}{2})^2 + I)\ddot{\theta} + m\dot{s}(l\cos\theta\cos\alpha - l\sin\theta\sin\alpha) + m\dot{s}\dot{\theta}(\dots) = \frac{\partial L}{\partial \theta} = \dot{s}\dot{\theta}(\dots) - mg\frac{l}{2}\sin\theta \rightarrow \ddot{\theta}(l\cos\theta\cos\alpha - l\sin\theta\sin\alpha) = -g\frac{1}{2}\sin\theta$$

A consistent solution to these equations requires  $\sin\alpha(\cos\theta\cos\alpha - \sin\theta\sin\alpha) = -\frac{1}{2}\sin\theta$  which gives  $\tan\theta = \frac{2\sin\alpha\cos\alpha}{2\sin\alpha^2 - 1} = -\tan(2\alpha) \rightarrow \theta = -2\alpha$ .

#### 3